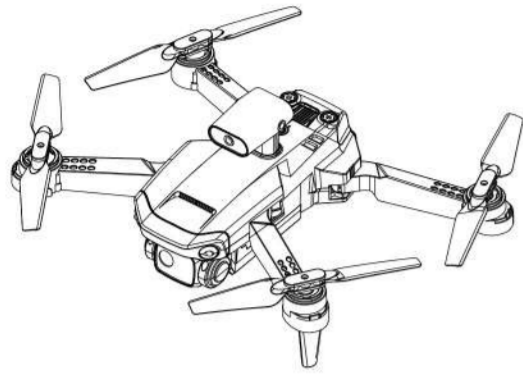


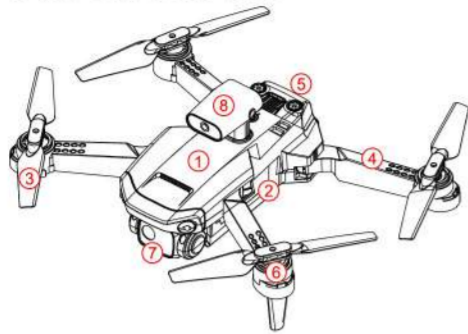
## 避障功能折叠无人机 使用说明书



### KNOW YOUR DRONE 认识你的无人机

The drone uses the 2.4G frequency, multiple-player can operate at the same time without interference. The drone can be controlled by remote to achieve flying, flipping, fine tuning, one-key take off, one-key landing, speed control, headless mode, calibration, obstacle avoidance, camera adjustment, emergency stop, light switch and other functions.

无人机采用2.4G频段，可多人同时操作而互不干扰。通过遥控器可操控无人机实现飞行、翻滚、微调、一键起飞、一键降落、速度、无头模式、校正、避障、摄像头调节、急停、灯光开关等功能。



- ① Upper Casing 机壳上盖
- ② Lower Casing 机壳下盖
- ③ Propeller 风叶
- ④ Arm 机臂
- ⑤ Battery 电池
- ⑥ Motor 电机
- ⑦ Camera 摄像头
- ⑧ Obstacle avoidance equipment 避障设备

\*Please read this manual carefully before operation and keep it properly for future reference.  
\*请在飞行前仔细阅读说明书并妥善保管以便日后参考。

### BATTERY INSTRUCTIONS 电池使用注意

- There is a certain risk when using lithium battery. It may cause fire, body injury or property loss. Users must be aware of the risks and take full responsibility of using battery improperly. 使用锂电池有一定风险，可能对人和财产造成重大损失，请谨慎使用，自行承担所有相关责任。
- If battery leakage occurs, please avoid contacting your eyes or skin with electrolyte. Once it happens, please wash your eyes with clean water and seek medical care immediately. 如果电池发生泄漏，请避免液体与皮肤和眼睛接触。若接触到皮肤，请立即以香皂和清水清洗。若接触到眼睛，请立即以大量冷水冲洗并立即就医。
- Please remove the plug immediately if you sense any peculiar smell, noise or smog. 如果充电器发出可疑异味、噪音或者烟雾，请立即拔掉电源。

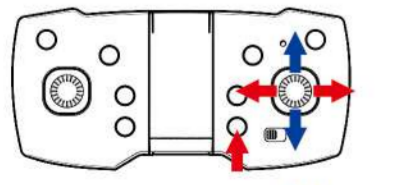
#### Battery Charging 充电

- Please use the charger from original factory to ensure your safe usage. 请使用原厂配送的专用充电器充电，严禁使用破损或其他品牌充电器。
- Do not charge dilant or outworn battery. 请勿对膨胀、泄漏或破损的电池充电。
- Do not over charge battery. Please unplug the charger once fully charged. 请勿对电池过度充电。当电池完全充满后，请拔掉充电器。
- Do not charge the battery next to inflammables, such as carpet, timber floor or wood furniture or on the surface of electro-conductive objects. Please always keep an eye on the battery when charging. 请勿在靠近易燃物（地毯、木地板、实木家具等）或导电的物体表面上充电。充电时请保持电池在视线范围内。
- Do not charge battery which not cool down yet. 切勿在使用产品后电池尚热时立即充电。
- The charging temperature should be between 0°C to 40°C. 电池充电的温度应该在0°C到40°C之间。

- Battery Recycling 回收**
- Do not dispose the battery as daily rubbish. Please familiarize yourself with the local garbage disposal method and dispose it according to the special requirement. 此设备由电子元件和电池构成。关于电子电器垃圾，请按照当地垃圾处理要求，进行特殊处理。

### FINE-TUNING FUNCTION

**微调功能**  
If the drone lean to one side when hovering, fine-tuning can be used to correct its direction. Press the fine-tuning button and hear a beep, then move the joystick in the opposite direction to adjust and calibrate until the aircraft does not deviate.  
If there is no operation for 5-6 seconds after entering the fine-tuning, the fine-tuning function will automatically exit. 当飞行器悬停时倾斜向某一方向，可使用微调修正方向。  
按下微调按键听到“滴”一声后，然后反方向拨动操作杆进行调节校准，直至飞行器不会偏飞为止。进入微调后如果5-6秒没有进行操作，微调功能就会自动退出。



- ① Forward/Backward Fine-tuning 前进/后退微调
- ② Left/Right Side Fly Fine-tuning 左/右侧飞微调

#### Notes 注意:

When the drone is within 30cm from the ground, it will be affected by the blade vortex made by itself and become unstable. This is "ground effect". The lower the drone is, the greater the effect will be. "地效反应" 指当无人机飞行越低时，地面反应影响则越大。当无人机在距离地面30cm以内的位置，无人机会受到自身桨叶气流的影响而变得不稳定。

### FAQ

#### 遇到问题不用慌

| PROBLEMS 问题              | CAUSES 原因   | SOLUTIONS 处理方法   |
|--------------------------|---|--|
| Control failure 遥控器失灵    | Not connect with the quadcopter battery. 无人机电池没连接<br>Too strong wind force. 风力太大  | Connect the quadcopter battery in right way. 把无人机电池按正确方向连接<br>Do not fly in windy days. The performance and the control of the quadcopter will be affected by the strong winds. 切勿在有风的情况下飞行。有风会对无人机造成局限，或会妨碍你的控制飞行 |
| Fail to ascend 无人机不能升高   | The rotation speed of main blades is too slow. 旋翼转动速度太慢<br>The battery of the quadcopter is not fully charged. 无人机未完成充电 | Push up the throttle joystick. 动力操纵杆向上推<br>Please full charge the quadcopter. 为无人机完全充电   |
| Landing too soon 无人机很快跌落 | The throttle stick is pulled down too fast. 过快将动力操纵杆回拉  | Pull down the throttle stick slowly to perform a smooth landing. 慢慢的回拉动力操纵杆让无人机慢慢着陆  |
| Out of control 失控        | Beyond the effective controlling distance. 超出有效遥控距离   | Ensure operation within the controllable distance: remote control of 100 meters and WIFI control of 40-50 meters. 确保遥控距离在100m内，WIFI操控在40-50m内  |

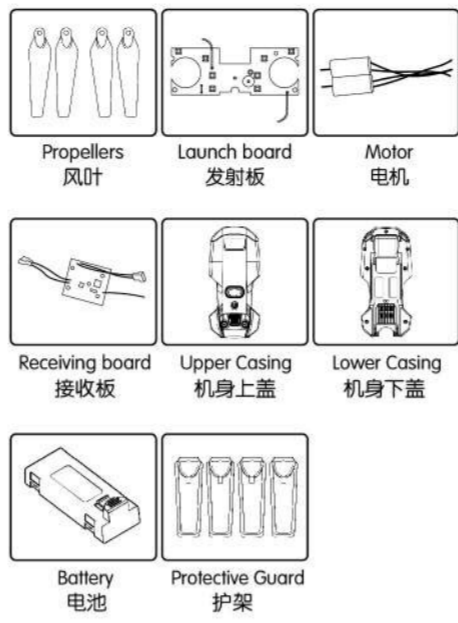
### ACCESSORIES 配件表



#### Notes 注意:

Please check the number of accessories carefully (as shown above) Please provide proof of purchase and contact the store for replacement if any missing parts.  
请仔细清点各配件及数量（如配件表），如果发现不齐全，请提供购买凭证，及时联系销售商家补货。

### OPTIONAL ACCESSORIES LIST 可另购配件表



#### Notes 注意:

If any of the above accessories are damaged during operation, you can contact the seller to purchase. 操作过程中，如有以上配件损坏，可自行联系卖家购买。

### PRE-FLIGHT PREPARATION 飞行前准备

#### 1. FLIGHT ENVIRONMENT 选择飞行环境



Indoor: Spacious spaces away from barriers, crowds or pets are preferred. 在室内飞行：请选择附近无障碍物、人群和宠物的开阔空间飞行。

Outdoor: Sunny, windless and breezy weathers are preferred. 在室外飞行：请选择晴朗无风的天气或微风天气飞行。

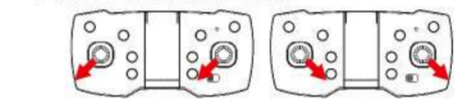


Please keep the drone in sight during the flight and keep it away from barriers, high-tension cables, trees and people. 飞行时请保持飞行器在视线范围之内，并远离障碍物、高压线、树木、人群等。

Do not fly in extreme environment, such as hotness, coldness, strong wind or heavy rain. 切勿在极端恶劣的环境下飞行，如过冷、过热、强风、暴雨等。

#### 电调版本

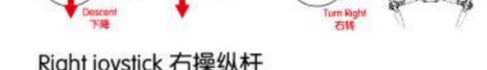
将左右操纵杆同时拨向左下方（或右下方）听到“滴”一声，此时无人机指示灯快闪，待指示灯常亮，矫正在执行校正命令时，必须与水平线平行的平稳状态下执行，否则会影响校正效果。



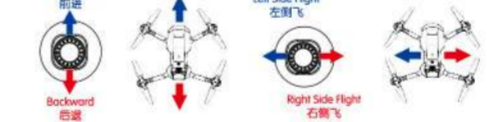
#### START YOUR FLIGHT 开始飞行

- One-key Ascend 一键起飞**  
Press the "One-key Ascend" button, the drone blades rotate and automatically fly to a height of 1.5 meters. 按下“一键起飞”按键，无人机风叶转动，自动飞到1.5米的高度。
- Basic Flight 基本飞行**  
Use the left joystick to control the flight altitude and turn left/right, and the right joystick to control the forward, backward, left and right side flight directions. 左操纵杆控制飞行高度与左右转方向，右操纵杆控制前进、后退以及左右侧飞方向。

#### Left joystick 左操纵杆

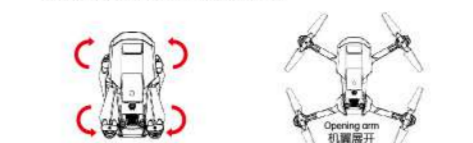


#### Right joystick 右操纵杆

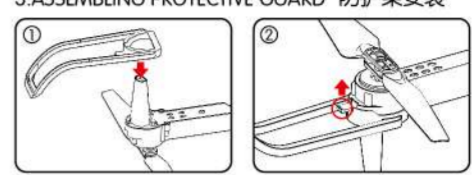


### 2. OPEN THE WINGS 打开机翼

**OPENING STEPS 打开机翼顺序:**  
① Open the front arm(close to camera) 先打开前机臂。（靠摄像头一侧）  
② Open the back arm 折后打开机臂，折叠时顺序相反。

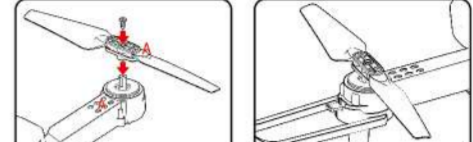


### 3. ASSEMBLING PROTECTIVE GUARD 防护架安装



Align the protective frame with the arm and install it (Figure 1), press it until it is in place, and then press the position (Figure 2) up to fasten the protective frame. 将保护架对准机臂安装（图1），按至到位，然后按（图2）位置往上按扣紧保护架。

### 4. ASSEMBLING PROPELLERS 风叶安装



Align the blades with the motor shaft and install them the arm identification must be consistent with the blade identification). Tighten the screw clockwise. 将风叶对准电机轴安装上去(机臂标识与风叶标识要一致)，顺时针拧紧螺丝。

### Obstacle Avoidance Mode (The obstacle avoidance function is only available when you purchase the obstacle avoidance version)



Press the button to turn on the obstacle avoidance mode, and press again to turn off the obstacle avoidance mode. Avoid obstacles on four sides and retreat in the opposite direction of the obstacle. 按下按键开启避障模式，再按一下关闭避障模式。四面避障，往障碍物相反方向退。  
It is recommended to turn on the obstacle avoidance function in an indoor flight environment with a length and width of 6 x 6 meters or more. When the UAV turns on the obstacle avoidance mode, the speed will slow down and the fast gear cannot be turned on. Therefore, it is recommended to fly indoors when the obstacle avoidance mode is turned on.  
建议在室内飞行环境长度宽6米x6米以上，开启避障功能。当无人机开启避障模式时，速度会变慢，且不能开启快速档，所以开启避障模式时建议在室内飞行。

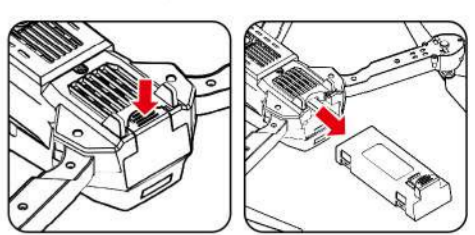
#### Flips & Rolls 翻滚

When the drone go to 1 meter above, press flipping button and move the right-joystick to the left or right side, it will flip to the corresponding direction. 无人机飞到1米以上高度后，点击翻滚键并将右操纵杆（方向舵）向左或右移动，可实现往此方向的翻滚动作。

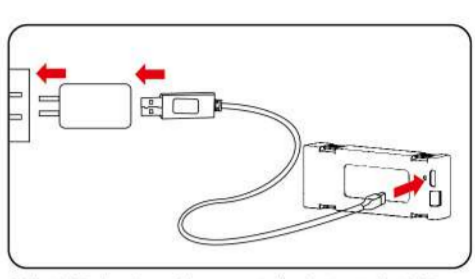
#### Right joystick 右操纵杆



### 5. BATTERY CHARGING FOR DRONE 机身充电方法



A. Remove the lithium battery from the bottom of the drone. 按下箭头指示的位置，把电池稍往外拉出，取出电池。



B. The USB charging cable connects the battery to the USB power port. USB充电线连接电池与USB充电接口

#### Notes 注意:

LED lights on when charging and red light turn off when full charging completes. Charging time is about 150 minutes. 充电时LED灯亮，充电结束时LED灯灭，充电时间约为2.5小时左右。

### Headless Mode 无头模式

The flight direction of drone is subjected to the direction of remote control. 1. When drone adjust the frequency, the drone is default as common mode. Then the indication light of drone is normally on. When you press the headless function key of remote control, the remote control beeps once and enters headless state. When you press the headless function key again, you listen to a long beep sound and the drone exits the headless mode. 2. In the headless state, operator doesn't need to identify the direction of nose, but control the drone according to the operating lever of remote control. 当无人机对频成功后，无人机默认为普通模式，此时无人机的指示灯为长亮状态，当按下遥控器上无头功能键后，遥控器发出“滴”一声表示进入无头状态，再按下无头功能键后听到“滴”长声为退出无头状态。在无头状态下，操控者无需去辨认无人机的机头方向，只根据遥控器的操作杆方向来控制飞行器。

#### Hover 悬停

When you release the left joystick (throttle) after the ascent/descent action, the drone will hover at a certain height. 左操纵杆让无人机上升后，松开左操纵杆，无人机仍会悬停在松开操纵杆时的高度。

#### Left joystick 左操纵杆



#### Camera angle adjustment 摄像头角度调节

During the flight of the drone, the camera angle can be adjusted through the camera adjustment button. (This function is only available in the camera ESC version) 无人机飞行过程中可通过摄像头调节按键来调节摄像头的角度。（摄像头电调版本才有此功能）

